# Bifurcation Theory and its applications in PDEs and Mathematical Biology Lecture 4: Hopf Bifurcations

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#### First word

#### G. H. Hardy (1877-1947)

A mathematician, like a painter or a poet, is a maker of patterns. The mathematician's patterns, like the painter's or the poet's, must be beautiful; the ideas, like the colours or the words, must fit together in a harmonious way.

#### Michael Atiyah (1929-)

The art in good mathematics, and mathematics is an art, is to identify and tackle problems that are both interesting and solvable.





For a continuous-time evolution equation  $\frac{du}{dt} = F(\lambda, u)$ , where  $u \in X$  (state space),  $\lambda \in \mathbb{R}$ , a stationary solution  $u_*$  is locally asymptotically stable (or just stable) if for any  $\epsilon > 0$ , then there exists  $\delta > 0$  such that when  $||u(0) - u_*||_X < \delta$ , then  $||u(t) - u_*||_X < \epsilon$  for all t > 0 and  $\lim_{t \to \infty} ||u(t) - u_*||_X = 0$ . Otherwise  $u_*$  is unstable.

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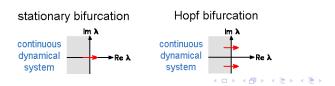
Bifurcation: when the parameter  $\lambda$  changes from  $\lambda_* - \varepsilon$  to  $\lambda_* + \varepsilon$ , the stationary solution  $u_*(\lambda)$  changes from stable to unstable; and other special solutions (stationary solutions, periodic orbits) may emerge from the known solution  $(\lambda, u_*(\lambda))$ .

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Stationary Bifurcation (transcritical/pitchfolk): if 0 is an eigenvalue of  $D_uF(\lambda_*,u_*)$ . It generates new stationary (steady state, equilibrium) solutions. Hopf Bifurcation: if  $\pm ki$  (k>0) is a pair of eigenvalues of  $D_uF(\lambda_*,u_*)$ . It generates new small amplitude periodic orbits.



### Poincaré-Andronov-Hopf Bifurcation Theorem

Consider ODE  $x' = f(\lambda, x)$ ,  $\lambda \in \mathbb{R}$ ,  $x \in \mathbb{R}^n$ , and f is smooth.

- (i) Suppose that for  $\lambda$  near  $\lambda_0$  the system has a family of equilibria  $x^0(\lambda)$ .
- (ii) Assume that its Jacobian matrix  $A(\lambda) = f_x(\lambda, x^0(\lambda))$  has one pair of complex eigenvalues  $\mu(\lambda) \pm i\omega(\lambda)$ ,  $\mu(\lambda_0) = 0$ ,  $\omega(\lambda_0) > 0$ , and all other eigenvalues of  $A(\lambda)$  have non-zero real parts for all  $\lambda$  near  $\lambda_0$ .

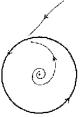
If  $\mu'(\lambda_0) \neq 0$ , then the system has a family of periodic solutions  $(\lambda(s), x(s))$  for  $s \in (0, \delta)$  with period T(s), such that  $\lambda(s) \to \lambda_0$ ,  $T(s) \to 2\pi/\omega(\lambda_0)$ , and  $||x(s) - x^0(\lambda_0)|| \to 0$  as  $s \to 0^+$ .







 $\beta = 0$ 



β>0

# Poincaré-Andronov-Hopf bifurcation







Henri Poincaré (1852-1912) Aleksandr Andronov (1901-1952) Eberhard Hopf (1902-1983)

Poincaré, H. [1894] "Les Oscillations 'Electriques" (Charles Maurain, G. Carr'e & C. Naud, Paris).

Andronov, A. A. [1929] "Les cycles limites de Poincaré et la théorie des oscillations auto-entretenues," Comptes Rendus Hebdomadaires de l'Acad'emie des Sciences 189, 559-561. limit cycle in 2-D systems

E. Hopf. [1942] "Abzweigung einer periodischen Losung von einer stationaren eines Differentialsystems". Ber. Verh. Sachs. Akad. Wiss. Leipzig. Math.-Nat. Kl. 95, (1943). no. 1, 3-22. limit cycle in *n*-D system

# Proof of Hopf bifurcation theorem: (1) transformation

Consider ODE  $x' = f(\lambda, x)$ ,  $\lambda \in \mathbb{R}$ ,  $x \in \mathbb{R}^n$ , and f is smooth. Assumptions:

- (i) Suppose that for  $\lambda$  near  $\lambda_0$  the system has a family of equilibria  $x^0(\lambda)$ .
- (ii) Assume that its Jacobian matrix  $A(\lambda) = f_{\chi}(\lambda, x^0(\lambda))$  has one pair of complex eigenvalues  $\mu(\lambda) \pm i\omega(\lambda)$ ,  $\mu(\lambda_0) = 0$ ,  $\omega(\lambda_0) = \omega_0 > 0$ , and all other eigenvalues of  $A(\lambda)$  have non-zero real parts for all  $\lambda$  near  $\lambda_0$ . (iii)  $\mu'(\lambda_0) \neq 0$ .

#### Preparation:

- 1. We can assume  $x^0(\lambda)=0$  (if not we can make a change of variables:  $y=x-x^0(\lambda)$ ), so from now we assume that  $f(\lambda,0)=0$  for  $\lambda$  near  $\lambda_0$ , and  $A(\lambda)=f_{\chi}(\lambda,0)$ .
- 2. A periodic solution x(t) satisfying  $x(t+\rho)=x(t)$  for a period  $\rho$ . We rescale the time  $s=t/\rho$ . Then the equation  $\frac{dx}{dt}=f(\lambda,x)$  becomes  $\frac{dx}{ds}=\rho f(\lambda,x)$ , and now x(s) satisfies x(s)=x(s+1) for a period 1. From now we consider the equation  $x'=\rho f(\lambda,x)$ , and we look for periodic solutions with period 1.

# Proof of Hopf bifurcation theorem: (2) Setup

Consider ODE  $x' = \rho f(\lambda, x)$ ,  $\lambda \in \mathbb{R}$ ,  $x \in \mathbb{R}^n$ ,

#### Assumptions:

- (i) Suppose that for  $\lambda$  near  $\lambda_0$ ,  $f(\lambda, 0) = 0$ .
- (ii) Assume that its Jacobian matrix  $A(\lambda)=f_{\scriptscriptstyle X}(\lambda,0)$  has one pair of complex eigenvalues  $\mu(\lambda)\pm i\omega(\lambda),\ \mu(\lambda_0)=0,\ \omega(\lambda_0)=\omega_0>0,$  and all other eigenvalues of  $A(\lambda)$  have non-zero real parts for all  $\lambda$  near  $\lambda_0$ .
- (iii)  $\mu'(\lambda_0) \neq 0$ .

Define the spaces

$$X = \{x \in C^{1}(\mathbb{R} : \mathbb{R}^{n}) : x(t+1) = x(t)\}, \quad Y = \{y \in C(\mathbb{R}, \mathbb{R}^{n}) : y(t+1) = y(t)\}.$$

and a mapping  $F: U \times V \times X \to Y$ , where  $\lambda_0 \in U \subset \mathbb{R}$ ,  $\rho_0 = 2\pi/\omega_0 \in V \subset \mathbb{R}$ ,

$$F(\lambda, \rho, x) = x' - \rho f(\lambda, x).$$

Since the eigenvalues are complex, hence we may consider the linearized equations in

$$X_{\mathbb{C}} = X + iX = \{x_1 + ix_2 : x_1, x_2 \in X\}, Y_{\mathbb{C}} = Y + iY.$$

# Proof of Hopf bifurcation theorem: (3) Linearization

Consider  $F: U \times V \times X \to Y$ , where  $\lambda_0 \in U \subset \mathbb{R}$ ,  $\rho_0 = 2\pi/\omega_0 \in V \subset \mathbb{R}$ ,

$$F(\lambda, \rho, x) = x' - \rho f(\lambda, x).$$

Then

$$F_x(\lambda,\rho,x)[w] = w' - \rho f_x(\lambda,x)w, \quad F_x(\lambda_0,\rho_0,0)[w] = w' - \frac{2\pi}{\omega_0} f_x(\lambda_0,0)w.$$

Kernel is two-dimensional:

$$\mathcal{N}(F_x(\lambda_0, \rho_0, 0)) = span \left\{ \exp(2\pi i t) v_0, \exp(-2\pi i t) \overline{v_0} \right\},\,$$

where  $f_x(\lambda_0,0)v_0=i\omega_0v_0$  and  $v_0(\neq 0)\in X_{\mathbb{C}}$ .

Range is codimensional two:

$$\mathcal{R}(F_{x}(\lambda_{0}, \rho_{0}, 0)) = \{ h \in Y_{\mathbb{C}} : \langle h \exp(2\pi i t), v_{0} \rangle = \langle h \exp(-2\pi i t), \overline{v_{0}} \rangle = 0 \},$$

or more precisely  $h=\sum_{k\in\mathbb{Z}}h_k\exp(2k\pi it)$  (Fourier series),  $h_{-k}=\overline{h_k},\ h_1=h_{-1}=0.$ 

# Proof of Hopf bifurcation theorem: (4) New spaces

For

$$X = \{x \in C^1(\mathbb{R} : \mathbb{R}^n) : x(t+1) = x(t)\}, \ Y = \{y \in C(\mathbb{R}, \mathbb{R}^n) : y(t+1) = y(t)\},$$

there are the space decompositions:

$$X = \mathcal{N}(F_x(\lambda_0, \rho_0, 0)) + Z, \quad Y = \mathcal{R}(F_x(\lambda_0, \rho_0, 0)) + W,$$

where Z and W are complements of  $\mathcal{N}(F_x(\lambda_0, \rho_0, 0))$  and  $\mathcal{R}(F_x(\lambda_0, \rho_0, 0))$  respectively.

Let 
$$w_0 = \frac{\exp(2\pi i t)v_0 + \exp(-2\pi i t)\overline{v_0}}{2} = \cos(2\pi t)u_0 \ (u_0 \in \mathbb{R}^n)$$
, and let  $X_1 = span\{w_0\} + Z$ .

We restrict 
$$F(\lambda, \rho, x) = x' - \rho f(\lambda, x)$$
 for  $x \in X_1$ . Then  $\mathcal{N}(F_x(\lambda_0, \rho_0, 0)) = span\{w_0\}$ .

Define 
$$Y_1 = \{y \in Y : \sum_{k \neq 1} y_k \exp(2k\pi it) + y_1 \cos(2\pi t)\}$$
. Then  $F : U \times V \times X_1 \to Y_1$  satisfies  $codim(\mathcal{R}(F_x(\lambda_0, \rho_0, 0))) = 1$ . Indeed  $\mathcal{R}(F_x(\lambda_0, \rho_0, 0)) = \{y \in Y_1 : y_1 \cdot x_0 = 0\}$ .

# Bifurcation from simple eigenvalue with two parameters

#### Theorem 7.6. [Crandall-Rabinowitz, 1971, JFA]

Let U be a neighborhood of  $(\lambda_0, u_0)$  in  $\mathbb{R} \times X$ , and let  $F: U \to Y$  be a continuously differentiable mapping such that  $F_{\lambda u}$  exists and continuous in U. Assume that  $F(\lambda, u_0) = 0$  for  $(\lambda, u_0) \in U$ . At  $(\lambda_0, u_0)$ , F satisfies

- **(F1)**  $dim \mathcal{N}(F_u(\lambda_0, u_0)) = codim \mathcal{R}(F_u(\lambda_0, u_0)) = 1$ , and
- **(F3)**  $F_{\lambda u}(\lambda_0, u_0)[w_0] \notin \mathcal{R}(F_u(\lambda_0, u_0))$ , where  $w_0 \in \mathcal{N}(F_u(\lambda_0, u_0))$ ,

Let Z be any complement of  $\mathcal{N}(F_u(\lambda_0,u_0))=span\{w_0\}$  in X. Then the solution set of  $F(\lambda,u)=0$  near  $(\lambda_0,u_0)$  consists precisely of the curves  $u=u_0$  and  $\{(\lambda(s),u(s)):s\in I=(-\epsilon,\epsilon)\}$ , where  $\lambda:I\to\mathbb{R},\ z:I\to Z$  are continuous functions such that  $u(s)=u_0+sw_0+sz(s),\ \lambda(0)=\lambda_0,\ z(0)=0.$ 

two-parameter case. [Shearer, 1978, MPCPS] Let U be a neighborhood of  $(\lambda_0, \rho_0, u_0)$  in  $\mathbb{R} \times \mathbb{R} \times X$ , and let  $F: U \to Y$  be a continuously differentiable mapping such that  $F_{\lambda u}$  and  $F_{\rho u}$  exist and continuous in U. Assume that  $F(\lambda, \rho, u_0) = 0$  for  $(\lambda, \rho, u_0) \in U$ . At  $(\lambda_0, \rho_0, u_0)$ , F satisfies

- **(F1)**  $dim \mathcal{N}(F_u(\lambda_0, \rho_0, u_0)) = codim \mathcal{R}(F_u(\lambda_0, \rho_0, u_0)) = 1$ , and
- **(F3)** there exists  $(a_1, a_2) \in \mathbb{R}^2$  such that

 $a_1F_{\lambda u}(\lambda_0,u_0)[w_0]+a_2F_{\rho u}(\lambda_0,\rho_0,u_0)[w_0]\not\in\mathcal{R}(F_u(\lambda_0,u_0)),$  where  $w_0\in\mathcal{N}(F_u(\lambda_0,u_0)),$  Let Z be any complement of  $\mathcal{N}(F_u(\lambda_0,u_0))=span\{w_0\}$  in X. Then the solution set of  $F(\lambda,\rho,u)=0$  near  $(\lambda_0,\rho_0,u_0)$  consists precisely of the set  $u=u_0$  and a curve  $\{(\lambda(s),\rho(s),u(s)):s\in I=(-\epsilon,\epsilon)\},$  where  $\lambda,\rho:I\to\mathbb{R},\ z:I\to Z$  are continuous functions such that  $u(s)=u_0+sw_0+sz(s),\ \lambda(0)=\lambda_0,\ \rho(0)=\rho_0,\ z(0)=0.$ 

# Proof of Hopf bifurcation theorem: (5)

For the mapping  $F: U \times V \times X_1 \to Y_1$ ,  $F(\lambda, \rho, x) = x' - \rho f(\lambda, x)$ , (F1) is satisfied.

$$F_{\rho u}(\lambda_0, \rho_0, 0)[w_0] = -f_x(\lambda_0, 0)w_0 = 0,$$
  
$$F_{\lambda u}(\lambda_0, \rho_0, 0)[w_0] = -\rho_0 f_{\lambda x}(\lambda_0, 0)w_0$$

Let  $f_x(\lambda,0)[w(\lambda)] = (\alpha(\lambda) + i\beta(\lambda))w(\lambda)$ . By differentiating with respect to  $\lambda$ , we get  $f_{\lambda x}(\lambda_0,0)[\exp(2\pi it)v_0] = (\alpha'(\lambda_0) + i\beta'(\lambda_0))\exp(2\pi it)v_0 - [f_x(\lambda_0,0)w'(\lambda_0) - (\alpha(\lambda_0) + i\beta(\lambda_0))w'(\lambda_0)]$ . Then  $f_{\lambda x}(\lambda_0,0)w_0 = \alpha'(\lambda_0)w_0 + z$  for some  $z \in \mathcal{R}(F_u(\lambda_0,\rho_0,0))$ , hence  $f_{\lambda x}(\lambda_0,0)w_0 \notin \mathcal{R}(F_u(\lambda_0,\rho_0,0))$  since  $\alpha'(\lambda_0) \neq 0$ .

From the bifurcation from simple eigenvalue with two-parameter theorem, all nontrivial solutions of  $F(\lambda, \rho, x) = 0$  are on a curve  $\{(\lambda(s), \rho(s), x(s)) : |s| < \delta\}$ .

In this way, we prove the periodic solutions in  $X_1$  are all on the curve  $\{(\lambda(s),\rho(s),x(s)):|s|<\delta\}$ . Note that with different choice of  $X_1$  and  $Y_1$ , different periodic solutions can be obtained, but they are only the same as the ones in  $X_1$  after a time phase shift.

# Dynamical system approach

Consider ODE  $x' = \rho f(\lambda, x)$ ,  $\lambda \in \mathbb{R}$ ,  $x \in \mathbb{R}^n$ ,

#### Assumptions:

- (i) Suppose that for  $\lambda$  near  $\lambda_0$ ,  $f(\lambda, 0) = 0$ .
- (ii) Assume that its Jacobian matrix  $A(\lambda)=f_{x}(\lambda,0)$  has one pair of complex eigenvalues  $\mu(\lambda)\pm i\omega(\lambda),\ \mu(\lambda_{0})=0,\ \omega(\lambda_{0})=\omega_{0}>0$ , and all other eigenvalues of  $A(\lambda)$  have non-zero real parts for all  $\lambda$  near  $\lambda_{0}$ .
- (iii)  $\mu'(\lambda_0) \neq 0$ .

More non-degeneracy condition:  $l_1(0) \neq 0$  (where  $l_1(\alpha)$  is the first Lyapunov coefficient), then according to the Center Manifold Theorem, there is a family of smooth two-dimensional invariant manifolds  $W_c^{\alpha}$  near the origin. The *n*-dimensional system restricted on  $W_c^{\alpha}$  is two-dimensional.

Moreover, under the non-degeneracy conditions, the *n*-dimensional system is locally topologically equivalent near the origin to the suspension of the normal form by the standard saddle, i.e.

$$\dot{y}_1 = \beta y_1 - y_2 + \sigma y_1(y_1^2 + y_2^2), \ \dot{y}_2 = y_1 + \beta y_2 + \sigma y_2(y_1^2 + y_2^2), \ (center manifold) \ \dot{y}^s = -y^s, \ (stable manifold), \ \dot{y}^u = +y^u \ (unstable manifold)$$

Whether Andronov-Hopf bifurcation is subcritical or supercritical is determined by  $\sigma$ , which is the sign of the "first Lyapunov coefficient"  $I_1(0)$  of the dynamical system near the equilibrium.

# First Lyapunov coefficient

Write the Taylor expansion of f(x,0) at x=0 as

$$f(x,0) = A_0x + \frac{1}{2}B(x,x) + \frac{1}{6}C(x,x,x) + O(\|x\|^4),$$

where B(x, y) and C(x, y, z) are the multilinear functions with components

$$B_j(x,y) = \sum_{k,l=1}^n \left. \frac{\partial^2 f_j(\xi,0)}{\partial \xi_k \partial \xi_l} \right|_{\xi=0} x_k y_l \ ,$$

$$C_j(x,y,z) = \sum_{k,l,m=1}^n \frac{\partial^3 f_j(\xi,0)}{\partial \xi_k \partial \xi_l \partial \xi_m} \bigg|_{\xi=0} x_k y_l z_m ,$$

where  $j=1,2,\ldots,n$ . Let  $q\in\mathbb{C}^n$  be a complex eigenvector of  $A_0$  corresponding to the eigenvalue  $i\omega_0$ :  $A_0q = i\omega_0q$ . Introduce also the adjoint eigenvector  $p \in \mathbb{C}^n$ :  $A_0^T p = -i\omega_0 p$ ,  $\langle p,q \rangle = 1$ . Here  $\langle p,q \rangle = \bar{p}^T q$  is the inner product in  $\mathbb{C}^n$ . Then (see, for example, [Kuznetsov, 2004, book])

$$I_1(0) = rac{1}{2\omega_0} \mathrm{Re} \left[ \langle p, \mathcal{C}(q,q,ar{q}) 
angle - 2 \langle p, \mathcal{B}(q,A_0^{-1}\mathcal{B}(q,ar{q})) 
angle + \langle p, \mathcal{B}(ar{q},(2i\omega_0 I_n - A_0)^{-1}\mathcal{B}(q,q)) 
angle 
ight]$$

where  $I_n$  is the unit  $n \times n$  matrix. Note that the value (but not the sign) of  $I_1(0)$ depends on the scaling of the eigenvector q. The normalization  $\langle q,q\rangle=1$  is one of the options to remove this ambiguity.

# Rosenzweig-MacArthur model

$$\frac{du}{dt} = u\left(1 - \frac{u}{k}\right) - \frac{muv}{1 + u}, \quad \frac{dv}{dt} = -\theta v + \frac{muv}{1 + u}$$
Nullcline:  $u = 0$ ,  $v = \frac{(k - u)(1 + u)}{m}$ ;  $v = 0$ ,  $\theta = \frac{mu}{1 + u}$ .

Solving  $\theta = \frac{mu}{1 + u}$ , one have  $u = \lambda \equiv \frac{\theta}{m - \theta}$ .

We take  $\lambda$  as a bifurcation parameter

Case 1:  $\lambda > k$ : (k, 0) is globally asymptotically stable

Case 2:  $(k-1)/2 < \lambda < k$ : (k,0) is a saddle, and  $(\lambda, v_{\lambda})$  is a globally stable equilibrium

Case 3:  $0 < \lambda < (k-1)/2$ : (k,0) is a saddle, and  $(\lambda, \nu_{\lambda})$  is an unstable equilibrium  $(\lambda = \lambda_0 = (k-1)/2$  is a Hopf bifurcation point)

$$A_0 = L_0(\lambda_0) := \left( \begin{array}{cc} \frac{\lambda_0(k-1-2\lambda_0)}{k(1+\lambda)} & -\theta \\ \frac{k-\lambda_0}{k(1+\lambda_0)} & 0 \end{array} \right).$$

# Normal form (1)

[Yi-Wei-Shi, 2009, JDE]

Eigenvector:  $A_0 q = i\omega_0 q$ ,  $A_0^* q^* = -i\omega q^*$ ,  $\langle q, q^* \rangle = 1$ .

$$q:=\left(\begin{array}{c} \mathbf{a}_0 \\ \mathbf{b}_0 \end{array}\right)=\left(\begin{array}{c} 1 \\ -i\omega_0/\theta \end{array}\right), \quad \text{and} \quad q^*:=\left(\begin{array}{c} \mathbf{a}_0^* \\ \mathbf{b}_0^* \end{array}\right)=\left(\begin{array}{c} 1/2 \\ -\theta i/(2\omega_0) \end{array}\right),$$

where  $\omega_0 = \sqrt{\theta/k}$ .

$$f(\lambda, u, v) = (u + \lambda) \left( 1 - \frac{u + \lambda}{k} \right) - \frac{m(u + \lambda)(v + v_{\lambda})}{1 + u + \lambda},$$
  

$$g(\lambda, u, v) = -\theta(v + v_{\lambda}) + \frac{m(u + \lambda)(v + v_{\lambda})}{1 + u + \lambda},$$
(1)

then we have,

$$c_{0} = \frac{-2(k-1)^{2} + 8i\omega_{0}k}{k(k-1)(k+1)}, \quad d_{0} = -\frac{4(k-1) + 8i\omega_{0}k}{k(k-1)(k+1)},$$

$$e_{0} = \frac{2(1-k)}{k(k+1)}, \quad f_{0} = -\frac{4}{k(k+1)}, \quad g_{0} = -h_{0} = -\frac{24(k-1) + 16i\omega_{0}k}{k(k-1)(k+1)^{2}}.$$
(2)

# Normal form (2)

and,

$$\langle q^*, Q_{qq} \rangle = \frac{4\theta\omega_0 k - (k-1)^2\omega_0 + 2\theta(3-k)i}{k(k-1)(k+1)\omega_0},$$

$$\langle q^*, Q_{q\bar{q}} \rangle = \frac{(1-k)\omega_0 - 2\theta i}{k(k+1)\omega_0},$$

$$\langle \bar{q}^*, Q_{qq} \rangle = -\frac{(k-1)^2\omega_0 + 2\theta k\omega_0 - 4\theta ki}{k(k-1)(k+1)\omega_0},$$

$$\langle \bar{q}^*, C_{qq\bar{q}} \rangle = \frac{-12(k-1)\omega_0 - 8\theta k\omega_0 + 4\theta(3k-5)i}{k(k-1)(k+1)^2\omega_0}.$$
(3)

$$H_{20} = \begin{pmatrix} c_{0} \\ d_{0} \end{pmatrix} - \langle q^{*}, Q_{qq} \rangle \begin{pmatrix} a_{0} \\ b_{0} \end{pmatrix} - \langle \overline{q}^{*}, Q_{qq} \rangle \begin{pmatrix} \overline{a_{0}} \\ \overline{b_{0}} \end{pmatrix} = 0,$$

$$H_{11} = \begin{pmatrix} e_{0} \\ f_{0} \end{pmatrix} - \langle q^{*}, Q_{q\overline{q}} \rangle \begin{pmatrix} a_{0} \\ b_{0} \end{pmatrix} - \langle \overline{q}^{*}, Q_{q\overline{q}} \rangle \begin{pmatrix} \overline{a_{0}} \\ \overline{b_{0}} \end{pmatrix} = 0,$$

$$(4)$$

which implies that  $w_{20} = w_{11} = 0$ . So

$$\langle q^*, Q_{w_{11},q} \rangle = \langle q^*, Q_{w_{20},\overline{q}} \rangle = 0. \tag{5}$$

# Normal form (3)

Therefore

$$\begin{aligned} \operatorname{Re}(c_{1}(\lambda_{0})) = & \operatorname{Re}\left\{\frac{i}{2\omega_{0}}\langle q^{*}, Q_{qq}\rangle \cdot \langle q^{*}, Q_{q\overline{q}}\rangle + \frac{1}{2}\langle q^{*}, C_{q,q,\overline{q}}\rangle\right\} \\ = & \frac{\theta(4\theta k - (k-1)^{2} - (3-k)(1-k))}{k^{2}(k-1)(k+1)^{2}\omega_{0}^{2}} + \frac{6\omega_{0}(1-k) - 4\theta\omega_{0}k}{k(k-1)(k+1)^{2}\omega_{0}} \\ = & \frac{\theta(4\theta k - (k-1)^{2} - (3-k)(1-k))}{k^{2}(k-1)(k+1)^{2}\omega_{0}^{2}} - \frac{6(k-1) + 4\theta k}{k(k-1)(k+1)^{2}} \\ = & \frac{4\theta k - (k-1)^{2} - (3-k)(1-k) - 6(k-1) - 4\theta k}{k(k-1)(k+1)^{2}} \\ = & -\frac{2(k-1)(k+1)}{k(k-1)(k+1)^{2}} = -\frac{2}{k(k+1)} < 0 \end{aligned}$$

The bifurcation is supercritical(resp. subcritical) if

$$\frac{1}{\alpha'(\lambda_0)} \operatorname{Re}(c_1(\lambda_0)) < 0(resp. > 0); \tag{7}$$

see also [Kuznetsov, 2004, book]



# Higher dimension

ODE model: 
$$\frac{dy}{dt} = f(\lambda, y), \quad y \in \mathbb{R}^n, f : \mathbb{R} \times \mathbb{R}^n \to \mathbb{R}^n$$

Equilibrium:  $y = y_0$  so that  $f(\lambda_0, y_0) = 0$ 

Jacobian Matrix:  $J = f_y(\lambda_0, y_0)$  is an  $n \times n$  matrix

#### Characteristic equation:

$$P(\lambda) = Det(\lambda I - J) = \lambda^n + a_1 \lambda^{n-1} + a_2 \lambda^{n-2} + \dots + a_{n-1} \lambda + a_n$$

Routh-Hurwitz criterion: complicated for general n

$$n = 1$$
:  $\lambda + a_1 = 0$ ,  $\underline{a_1 > 0}$ 

$$n=2$$
:  $\lambda^2+a_1\lambda+\overline{a_2=0}$ ,  $a_1>0$ ,  $a_2>0$  Trace-determinant plane

$$n = 3$$
:  $\lambda^3 + a_1\lambda^2 + a_2\lambda + \overline{a_3} = 0$ ,  $a_1 > 0$ ,  $a_2 > \frac{a_3}{a_1}$ ,  $a_3 > 0$ 

$$n = 4: \ \lambda^4 + a_1\lambda^3 + a_2\lambda^2 + a_3\lambda + a_4 = 0, \ a_1 > 0, \ a_2 > \frac{a_3^2 + a_1^2a_4}{a_1a_3}, \ a_3 > 0, \ a_4 > 0$$

 $n \ge 5$ : check books

# 3D system

$$n = 3$$
:  $\lambda^3 + a_1\lambda^2 + a_2\lambda + a_3 = 0$ ,  $a_1 > 0$ ,  $a_2 > \frac{a_3}{a_1}$ ,  $a_3 > 0$ 

Hopf bifurcation point:  $a_1 > 0$ ,  $a_3 > 0$ ,  $a_1a_2 - a_3 = 0$ . Eigenvalues:  $\lambda_1 = \beta i$ ,  $\lambda_2 = -\beta i$ , and  $\lambda_3 = -\alpha$  (for  $\alpha, \beta > 0$ ) Then

$$a_1 = -(\lambda_1 + \lambda_2 + \lambda_3) = \alpha > 0, \ a_2 = \lambda_1 \lambda_2 + \lambda_1 \lambda_3 + \lambda_2 \lambda_3 = \beta^2 > 0, \ a_3 = -\lambda_1 \lambda_2 \lambda_3 = \alpha \beta^2 > 0.$$

And  $a_1 a_2 - a_3 = 0$ .

Example: (Lorenz system)  $x' = \sigma(y - x)$ , y' = rx - y - xz, z' = xy - bz.

#### Basic dynamics:

equilibria:  $C_0=(0,0,0)$ ,  $C_\pm=(\pm\sqrt{b(r-1)},\pm\sqrt{b(r-1)},r-1)$ . global stability: when 0< r<1,  $C_0$  is globally stable

Jacobian: 
$$\begin{pmatrix} -\sigma & \sigma & 0 \\ r-z & -1 & -x \\ y & x & -b \end{pmatrix}$$
, characteristic equation at  $C_{\pm}$ :

$$\lambda^3 + (\sigma + b + 1)\lambda^2 + (r + \sigma)b\lambda + 2b\sigma(r - 1) = 0$$

Hopf bifurcation:  $a_1 = \sigma + b + 1 > 0$ ,  $a_3 = 2b\sigma(r - 1) > 0$ ,  $a_1a_2 - a_3 = (\sigma + b + 1)(r + \sigma)b - 2b\sigma(r - 1) = 0$ 

Hopf bifurcation point: 
$$r = \frac{\sigma(\sigma + b + 3)}{\sigma - b - 1}$$
. It is a subcritical bifurcation.



# Global bifurcation of periodic orbits

Consider ODE  $x' = f(\lambda, x)$ ,  $\lambda \in \mathbb{R}$ ,  $x \in \mathbb{R}^n$ , and f is smooth.

#### **Assumptions:**

- (i) Suppose that for  $\lambda$  near  $\lambda_0$  the system has a family of equilibria  $x^0(\lambda)$ .
- (ii) Assume that its Jacobian matrix  $A(\lambda)=f_{x}(\lambda,x^{0}(\lambda))$  has one pair of complex eigenvalues  $\mu(\lambda)\pm i\omega(\lambda),\ \mu(\lambda_{0})=0,\ \omega(\lambda_{0})=\omega_{0}>0$ , and all other eigenvalues of  $A(\lambda)$  have non-zero real parts for all  $\lambda$  near  $\lambda_{0}$ .
- (iii)  $\mu'(\lambda_0) \neq 0$ .

Let  $x(\lambda, t; x_0)$  be the solution of the equation with initial condition  $x(\lambda, 0; x_0) = x_0$ .

We say  $(\lambda, x_0)$  is stationary if  $x(\lambda, t; x_0) = x_0$  for all  $t \ge 0$ .

We say  $(\lambda, x_0)$  is periodic if it is not stationary, and there exists T > 0 such that  $x(\lambda, T; x_0) = x_0$ .

If  $(\lambda, x_0)$  is periodic, then all positive T > 0 such that  $x(\lambda, T; x_0) = x_0$  are the periods. The smallest positive period is the least period.

#### Define

$$\Sigma = \{(\lambda, T, x_0) \in \mathbb{R} \times (0, \infty) \times \mathbb{R}^n : x(\lambda, T; x_0) = x_0 \text{ and } (\lambda, x_0) \text{ is periodic} \}.$$

# Global bifurcation of periodic orbits

#### [Alexander-Yorke, 1978, AJM]

Consider ODE  $x' = f(\lambda, x)$ ,  $\lambda \in \mathbb{R}$ ,  $x \in \mathbb{R}^n$ , and f is smooth.

#### Assumptions:

- (i) Suppose that for  $\lambda$  near  $\lambda_0$  the system has a family of equilibria  $x^0(\lambda)$ .
- (ii) Assume that its Jacobian matrix  $A(\lambda)=f_{\chi}(\lambda,x^0(\lambda))$  has one pair of complex eigenvalues  $\mu(\lambda)\pm i\omega(\lambda),\ \mu(\lambda_0)=0,\ \omega(\lambda_0)=\omega_0>0$ , and all other eigenvalues of  $A(\lambda)$  have non-zero real parts for all  $\lambda$  near  $\lambda_0$ .
- (iii)  $\mu'(\lambda_0) \neq 0$ .

#### Define

$$S = \{(\lambda, T, x_0) \in \mathbb{R} \times (0, \infty) \times \mathbb{R}^n : x(\lambda, T; x_0) = x_0 \text{ and } (\lambda, x_0) \text{ is periodic}\}.$$

- ① There exists connected component  $S_0$  of  $S \cup \{y_0 \equiv (\lambda_0, 2\pi/\omega_0, x^0(\lambda_0))\}$  containing  $y_0$  and at least one periodic solution. Near  $y_0$ , every  $y = (\lambda, T, x_0)(\neq y_0) \in S_0$  is periodic with the least period T.
- ② One or both of the following are satisfied: (i)  $S_0$  is not contained in any compact subset of  $\mathbb{R} \times (0, \infty) \times \mathbb{R}^n$ ; (ii) there exists a point  $(\lambda_*, T_*, x_{0*}) \in \overline{S_0} \setminus S_0$ .
- **③** For any  $(\lambda_*, T_*, x_{0*}) \in \overline{S} \setminus S$ ,  $(\lambda_*, x_{0*})$  is stationary. For any  $\varepsilon > 0$ , there is a neighborhood  $U_{\varepsilon}$  of  $(\lambda_*, T_*, x_{0*})$  such that for any  $(\lambda, T, x_0) \in U_{\varepsilon} \cap S$ , all points of the orbit  $x(\lambda, t; x_0)$  are of distance less than  $\varepsilon$  from  $x_{0*}$ .

#### Remarks

- ① The assumptions (ii) and (iii) can be generalized to: there are k pairs of purely imaginary eigenvalues of  $A(\lambda_0)$  in form  $\{i\beta_j\omega_0:1\le j\le k\}$  with  $1\le \beta_1\le \beta_2\le \cdots \le \beta_k$ , and the change of the number of such eigenvalues with positive real part from  $\lambda=\lambda_0-\varepsilon$  to  $\lambda=\lambda_0+\varepsilon$  is odd.
- The proofs of the result use homotopy theory or Fuller index or other topological invariants.
- $\odot$  The theorem states that either the connected component  $S_0$  contains another stationary solution, or it is unbounded in the sense that

$$\sup_{(\lambda,T,x_0)\in S_0,t\in\mathbb{R}}\left(|\lambda|+|T|+|T^{-1}|+|x(\lambda,t;x_0)|\right)=\infty.$$

- ① If  $(\lambda, T, x_0) \in S_0$ , then T is not necessarily the least period of the periodic solution  $x(\lambda, T; x_0)$ . If  $i\omega_0$  is an simple simple eigenvalue of  $A(\lambda_0)$ , then near  $y_0$ , T is the least period. Note that if T is a period, so is kT for  $k \in \mathbb{N}$ , so the periods are always unbounded. The main point of the theorem is the periods can be unbounded continuously.
- **3** The notation  $x(\lambda,t;x_0)$  is a periodic solution, and  $\{x(\lambda,t;x_0):t\in\mathbb{R}\}$  ia a periodic orbit. It is clear that for any  $x_t=x(\lambda,t;x_0),\ x(\lambda,t;x_t)$  is also a periodic solution, but it has the same orbit as  $x(\lambda,t;x_0)$ . For a fixed  $\lambda$ , the periodic solution is never unique, but the periodic orbit may be unique. Hence it is wrong to say "there exists at least two periodic solutions" in a theorem, and you should say "there exists at least two periodic orbits".

### Example

Rosenzweig-MacArthur model

$$\frac{du}{dt} = u\left(1 - \frac{u}{k}\right) - \frac{muv}{1 + u}, \quad \frac{dv}{dt} = -\theta v + \frac{muv}{1 + u}.$$

Parameter: 
$$\lambda \equiv \frac{\theta}{m-\theta}$$
.

Equilibria: (0,0), (k,0), (
$$\lambda$$
,  $v_{\lambda}$ ) where  $v_{\lambda} = \frac{(k-\lambda)(1+\lambda)}{m}$ 

Case 1:  $\lambda \ge k$ : (k,0) is globally asymptotically stable

Case 2:  $(k-1)/2 < \lambda < k$ :  $(\lambda, v_{\lambda})$  is a globally stable equilibrium

Case 3:  $0 < \lambda < (k-1)/2$ : (k,0) and  $(\lambda, v_{\lambda})$  are both unstable

 $(\lambda = \lambda_0 = (k-1)/2$  is a Hopf bifurcation point)

There exists a branch of periodic orbits  $S_0=\{(\lambda,T,x_0):0<\lambda<(k-1)/2\}.$  One can show that  $|x_0|$  is bounded for  $S_0$ , so T is unbounded when  $\lambda\to 0$ . In this case, the limit of the orbits  $\{x(\lambda,t;x_0):t\in\mathbb{R}\}$  when  $\lambda\to 0$  is not an orbit. [Hsu-Shi, 2009, DCDS-B]

Sometimes if  $T \to \infty$  as  $\lambda \to \lambda_*$ , the limit of the orbits  $\{x(\lambda,t;x_0):t\in\mathbb{R}\}$  when  $\lambda \to \lambda_*$  is a homoclinic orbit or a heteroclinic loop of the system. [Wang-Shi-Wei, 2011, JMB]

# Abstract version: Hopf bifurcation theorem

#### [Crandall-Rabinowitz, ARMA, 1977]

Consider an evolution equation in Banach space X:

$$\frac{du}{dt} + Lu + f(\mu, u) = 0. \tag{8}$$

Here X is a Banach space, and  $X_{\mathbb{C}}=X+iX$  is the complexification of  $X;L:X\to X$  is a linear operator and it can be extended to  $X_{\mathbb{C}}$  naturally. The spectral set  $\sigma(L)\subseteq \mathbb{C}$ , and  $\lambda\in\sigma(L)$  if and only if  $\bar{\lambda}\in\sigma(L)$ .

Conditions on L (HL):

- **1** -L is the infinitesimal generator of a strongly continuous semigroup T(t) on X;
- 2 T(t) is a holomorphic (analytic) semigroup on  $X_{\mathbb{C}}$ ;
- (3)  $(\lambda I L)^{-1}$  is compact for  $\lambda \notin \sigma(L)$ ;
- 4 i is a simple eigenvalue of L (with eigenvector  $w_0 \neq 0$ );
- **5**  $ni \notin \sigma(L)$  for n = 0 and  $n = 2, 3, \cdots$

# Abstract version: Hopf bifurcation theorem

Conditions on f: (Hf)

- ① There exists  $\alpha \in (0,1)$  and a neighborhood U of  $(\mu,u)=(0,0)$  in  $\mathbb{R} \times X^{\alpha}$  such that  $f \in C^2(U,X)$ ;
- ②  $f(\mu,0) = 0$  for  $(\mu,0) \in U$  and  $f_u(0,0) = 0$ .

(HL) and (Hf) imply that there exists  $C^1$  functions  $(\beta(\mu), \nu(\mu))$  for  $\mu \in (-\delta, \delta)$  such that

$$[L + f_u(\mu, 0)]v(\mu) = \beta(\mu)v(\mu), \quad \beta(0) = i, \quad v(0) = w_0.$$

Condition on  $\beta$ : (H $\beta$ )

**1** Re  $\beta'(0) \neq 0$ .

Rescaling  $au=
ho^{-1}t$ : change the period of periodic orbit to a parameter

$$\frac{du}{d\tau} + \rho Lu + \rho f(\mu, u) = 0. \tag{9}$$

Looking for a period-1 periodic orbit for the rescaled equation.

Convert it to integral equation  $u(\tau)$  is a solution to (9) for  $\tau \in [0, r]$  if and only if, for  $\tau \in [0, r]$ ,

$$F(\rho,\mu,u) \equiv u(\tau) - T(\rho\tau)u(0) + \rho \int_0^\tau T(\rho(\tau-\xi))f(\mu,u(\xi))d\xi = 0.$$

# Abstract version: Hopf bifurcation theorem

Let  $C_{2\pi}(\mathbb{R}, X_{\alpha})$  be the set of  $2\pi$ -periodic continuous functions, and let  $C_0([0, 2\pi], X_{\alpha}) = \{h : [0, 2\pi] \to X_{\alpha}, h(0) = 0, h \text{ is continuous }\}$ . Then

$$F(
ho,\mu,u)\equiv u( au)-T(
ho au)u(0)+
ho\int_0^ au T(
ho( au-\xi))f(\mu,u(\xi))d\xi$$

is well-defined so that  $F: \mathbb{R} imes \mathbb{R} imes C_{2\pi}(\mathbb{R}, X_{lpha}) o C_0([0, 2\pi], X_{lpha}).$ 

Theorem. Let (HL), (Hf) and (H $\beta$ ) be satisfied. Then there exist  $\varepsilon, \eta > 0$  and  $C^1$  functions  $(\rho, \mu, u) : (-\eta, \eta) \to \mathbb{R} \times \mathbb{R} \times C_{2\pi}(\mathbb{R}, X_{\alpha})$  such that

- **1**  $F(\rho(s), \mu(s), u(s)) = 0$  for  $|s| < \eta$ .
- ②  $\mu(0) = 0$ , u(0) = 0,  $\rho(0) = 1$  and  $u(s) \neq 0$  for  $0 < |s| < \eta$ .
- ③ If  $(\mu_1,u_1) \in \mathbb{R} \times C(\mathbb{R},X_\alpha)$  is a solution of (8) with period  $2\pi\rho_1$ , where  $|\rho_1-1|<\varepsilon$ ,  $|\mu_1|<\varepsilon$ , and  $||u_1||_\alpha<\varepsilon$ , then there exist  $s\in[0,\eta)$  and  $\theta\in[0,2\pi)$  such that  $u(\rho_1\tau)=u(s)(\tau+\theta)$  for  $\tau\in\mathbb{R}$ .

Note: There is a relation between the solutions with  $s \in (0, \eta)$  and  $s \in (-\eta, 0)$ , and they are the same orbit with different phases.

# Reaction-Diffusion systems

#### [Yi-Wei-Shi, 2009, JDE]

A general reaction-diffusion system subject to Neumann boundary condition on spatial domain  $\Omega=(0,\ell\pi).$ 

$$\begin{cases} u_{t} - d_{1}u_{xx} = f(\lambda, u, v), & x \in (0, \ell\pi), \ t > 0, \\ v_{t} - d_{2}v_{xx} = g(\lambda, u, v), & x \in (0, \ell\pi), \ t > 0, \\ u_{x}(0, t) = v_{x}(0, t) = 0, \ u_{x}(\ell\pi, t) = v_{x}(\ell\pi, t) = 0, & t > 0, \\ u(x, 0) = u_{0}(x), \ v(x, 0) = v_{0}(x), & x \in (0, \ell\pi), \end{cases}$$
(10)

where  $d_1, d_2, \lambda \in \mathbb{R}^+$ ,  $f, g: \mathbb{R} \times \mathbb{R}^2 \to \mathbb{R}$  are  $C^k(k \geq 3)$  with  $f(\lambda, 0, 0) = g(\lambda, 0, 0) = 0$ . Define the real-valued Sobolev space

$$X := \{(u, v) \in H^2(0, \ell\pi) \times H^2(0, \ell\pi) | (u_x, v_x)|_{x=0, \ell\pi} = 0\}.$$
 (11)

The linearized operator of the steady state system of (10) evaluated at  $(\lambda,0,0)$  is,

$$L(\lambda) := \begin{pmatrix} d_1 \frac{\partial^2}{\partial x^2} + A(\lambda) & B(\lambda) \\ C(\lambda) & d_2 \frac{\partial^2}{\partial x^2} + D(\lambda) \end{pmatrix}, \tag{12}$$

with the domain  $D_{L(\lambda)} = X_{\mathbb{C}}$ , where  $A(\lambda) = f_u(\lambda, 0, 0)$ ,  $B(\lambda) = f_v(\lambda, 0, 0)$ ,

$$C(\lambda)=g_u(\lambda,0,0), \text{ and } D(\lambda)=g_v(\lambda,0,0).$$

# Hopf bifurcations

We assume that for some  $\lambda_0 \in \mathbb{R}$ , the following condition holds:  $(\mathbf{H}_1)$ : There exists a neighborhood O of  $\lambda_0$  such that for  $\lambda \in O$ ,  $L(\lambda)$  has a pair of complex, simple, conjugate eigenvalues  $\alpha(\lambda) \pm i\omega(\lambda)$ , continuously differentiable in  $\lambda$ , with  $\alpha(\lambda_0) = 0$ ,  $\omega(\lambda_0) = \omega_0 > 0$ , and  $\alpha'(\lambda_0) \neq 0$ ; all other eigenvalues of  $L(\lambda)$  have non-zero real parts for  $\lambda \in O$ .

Theorem. Suppose that the assumption  $(\mathbf{H}_1)$  holds. Then there is a family of periodic orbits  $S = \{(\lambda(s), T(s), u(s, x, t), v(s, x, t)) : 0 < s < \delta\}$  with  $\lambda(s), T(s), u(s, \cdot, \cdot), v(s, \cdot, \cdot)$  differentiable in s, (u(s, x, t + T(s)), v(s, x, t + T(s))) = (u(s, x, t), v(s, x, t)), and

$$\lim_{s\to 0} \lambda(s) = \lambda_0, \lim_{s\to \infty} T(s) = \frac{2\pi}{\omega_0}, \lim_{s\to 0} |u(s,x,t)| + |v(s,x,t)| = 0,$$

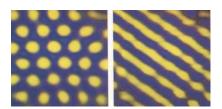
uniformly for  $x \in [0, \ell \pi]$  and  $t \in \mathbb{R}$ . All periodic orbits of the system are time phase shifts of the ones on S.

Normal form calculations: [Yi-Wei-Shi, 2009, JDE]

# Turing patterns in real experiment

The first experimental evidence of Turing pattern was observed in 1990, nearly 40 years after Turing's prediction, by the Bordeaux group in France, on the chlorite-iodide-malonic acid-starch (CIMA) reaction in an open unstirred gel reactor. This observation represents a significant breakthrough for one of the most fundamental ideas in morphogenesis and biological pattern formation.

[Castets, et.al., 1990] Experimental evidence of a sustained Turing-type equilibrium chemical pattern. *Phys. Rev. Lett.* **64**.



# Modeling for for CIMA reaction

[Lengyel-Epstein, 1991] Modeling of Turing Structures in the Chlorite-Iodide-Malonic Acid-Starch Reaction System. *Science*.

$$MA + I_2 \rightarrow IMA + I^- + H^+,$$
  
 $CIO_2 + I^- \rightarrow CIO_2 + (1/2)I_2,$   
 $CIO_2 + 4I^- + 4H^+ \rightarrow CI^- + 2I_2 + 2H_2O$ 

 $[\mathit{CIO}_2]$ ,  $[\mathit{I}_2]$  and  $[\mathit{MA}]$  varying slowly, assumed to be constant Let  $I^- = X$ ,  $\mathit{CIO}_2 = Y$  and  $\mathit{I}_2 = A$ . Then the reaction becomes

$$A \xrightarrow{k_1} X$$
,  $X \xrightarrow{k_2} Y$ ,  $4X + Y \xrightarrow{k_3} P$ 

Reaction rates  $k_1$ ,  $k_2$  are constants, and  $k_3$  is proportional to  $\frac{[X] \cdot [Y]}{u + [X]^2}$ 

# Reaction-diffusion system for CIMA reaction

Nondimensionalized reaction-diffusion system:

$$\begin{cases} u_{t} = \Delta u + a - u - \frac{4uv}{1 + u^{2}}, & x \in \Omega, t > 0, \\ v_{t} = \sigma[c\Delta v + b(u - \frac{1}{1 + u^{2}})], & x \in \Omega, t > 0, \\ \partial_{\nu} u = \partial_{\nu} v = 0, & x \in \partial\Omega, t > 0, \\ u(x, 0) = u_{0}(x) > 0, v(x, 0) = v_{0}(x) > 0, & x \in \Omega, \end{cases}$$

Here  $[I^-] = u(x,t)$ ,  $[CIO_2] = v(x,t)$ ,  $x \in \Omega$  (reactor) no flux boundary condition: closed chemical reaction  $a,b,\sigma,c>0$ . Key parameter: a>0 (the feeding rate) [Lengyel-Epstein, 1991]

Change of parameters:

$$d = \frac{c}{b}, \quad m = \sigma b, \quad \alpha = \frac{a}{5},$$

New equation:

$$\begin{cases} u_t = \triangle u + 5\alpha - u - \frac{4uv}{1+u^2}, & x \in \Omega, t > 0, \\ v_t = m\left(d\Delta v + u - \frac{uv}{1+u^2}\right), & x \in \Omega, t > 0. \end{cases}$$

# Turing bifurcation in 1-D problem

For simplicity, we assume that n=1 and  $\Omega=(0,\ell\pi)$ .

$$\begin{cases} u_t = u_{xx} + \lambda f(u, v), & x \in (0, \ell\pi), \ t > 0, \\ v_t = dv_{xx} + \lambda g(u, v), & x \in (0, \ell\pi), \ t > 0, \\ u_x(t, 0) = u_x(t, \ell\pi) = v_x(t, 0) = v_x(t, \ell\pi) = 0, & t > 0, \\ u(0, x) = u_0(x), \ v(0, x) = v_0(x), & x \in (0, \ell\pi). \end{cases}$$

Equilibrium point:  $f(u_0, v_0) = g(u_0, v_0) = 0$ 

Linearized equation:

$$L\left(\begin{array}{c}\phi\\\psi\end{array}\right) = \left(\begin{array}{c}\phi_{xx}\\d\psi_{xx}\end{array}\right) + \lambda \left(\begin{array}{cc}f_u&f_v\\g_u&g_v\end{array}\right) \left(\begin{array}{c}\phi\\\psi\end{array}\right)$$

Condition for Turing instability:  $f_u < 0$ ,  $g_v > 0$ , 0 < d < 1,

$$0 < d < \frac{\lambda [g_v k^2 - \lambda D_1]}{k^2 (k^2 - \lambda f_u)} \equiv d_k(\lambda)$$
 (bifurcation point)

# Turing bifurcation in CIMA model

$$\begin{cases} u_{t} = u_{xx} + 5\alpha - u - \frac{4uv}{1 + u^{2}}, & x \in (0, \ell\pi), \ t > 0, \\ v_{t} = m \left( dv_{xx} + u - \frac{uv}{1 + u^{2}} \right), & x \in (0, \ell\pi), \ t > 0, \\ u_{x}(x, t) = v_{x}(x, t) = 0, & x = 0, \ell\pi, \ t > 0, \\ u(x, 0) = u_{0}(x), \ v(x, 0) = v_{0}(x), & x \in (0, \ell\pi), \end{cases}$$

$$(13)$$

Constant equilibrium: 
$$(u_*, v_*) = (\alpha, 1 + \alpha^2)$$
  
Jacobian at  $(u_*, v_*)$ :  $J = \frac{1}{1 + \alpha^2} \begin{pmatrix} 3\alpha^2 - 5 & -4\alpha \\ 2\alpha^2 & -\alpha \end{pmatrix}$ .

Assume 0 <  $3\alpha^2-5<\alpha$  (or 1.291  $<\alpha<1.468)$ 

$$f_u>0, \ g_v<0, \ D_1=f_ug_v-f_vg_u>0 \ \ \text{and} \ \ f_u+g_v<0.$$

Bifurcation points: 
$$d_j = \frac{\alpha}{1 + \alpha^2} \cdot \frac{5 + \lambda_j}{\lambda_j (f_0 - \lambda_j)}$$
,

where 
$$f_0 = \frac{3\alpha^2 - 5}{1 + \alpha^2}$$
, and  $\lambda_j = j^2/\ell^2$ .

[Ni-Tang, 2005] also true for higher dimensions



# Global Turing Bifurcation for CIMA reaction

#### [Ni-Tang, 2005] Trans. Amer. Math. Soc.:

- (A) For d > 0 small,  $(u_*, v_*)$  is the only steady state solution;
- (B) All non-negative steady state solution satisfies  $0 < u(x) < 5\alpha$ ,  $0 < v(x) < 1 + 25\alpha^2$ .

#### [Jang-Ni-Tang, 2004] J. Dynam. Diff. Equa.:

- (C) Each connected component bifurcated from  $(d_j, u_*, v_*)$  is unbounded in the space of (d, u, v), and its projection over d-axis covers  $(d_j, \infty)$ .
- (D) For each  $d > \min\{d_j\}$  and  $d \neq d_k$ , there exists a non-constant steady state solution.

Their results are only for steady state solutions.

- (i) What are the dynamical behavior of the solutions?
- (ii) What about the oscillatory dynamics?
- (iii) What is the impact of the feeding rate  $\alpha > 0$ ? (Turing instability shows the impact of the diffusion coefficient d > 0)

# **ODE** Dynamics

Kinetic equation:

$$\begin{cases} u_t = 5\alpha - u - \frac{4uv}{1 + u^2}, & t > 0, \\ v_t = m\left(u - \frac{uv}{1 + u^2}\right), & t > 0, \end{cases}$$

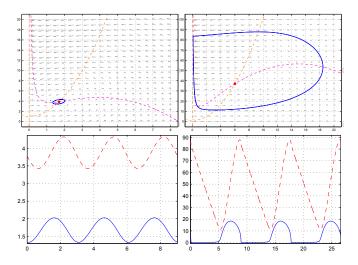
Equilibrium:  $(u_*, v_*) = (\alpha, 1 + \alpha^2)$ 

- (i) For  $\alpha < \alpha_0 = \frac{m + \sqrt{m^2 + 60}}{6}$ ,  $(u_*, v_*)$  is locally stable;
- (ii) For  $\alpha > \alpha_0$ ,  $(u_*, v_*)$  is locally unstable, and the system has a periodic orbit  $(\alpha_0$  is a Hopf bifurcation point);
- (iii) For  $\alpha < \sqrt{27}/5 \approx 1.0392$ ,  $(u_*, v_*)$  is globally asymptotically stable (even for R-D system in higher dimensional domains)

Comparison of bifurcation points:

$$\frac{\sqrt{27}}{5} \approx 1.0392 < \sqrt{\frac{5}{3}} \approx 1.291 < \frac{m + \sqrt{m^2 + 60}}{6} \text{ (if } m > 0)$$

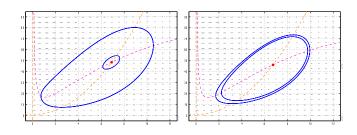
# Limit cycle generated from Hopf bifurcation



Here m=2,  $\alpha_0=5/3\approx 1.667$ . Left:  $\alpha=1.69$ ; Right:  $\alpha=6$ .

Top: phase portraits; Bottom: solution curves (solid curve u(t), dotted curve:

### Multiple periodic orbits for ODE



$$u' = 5\alpha - u - \frac{4uv}{1 + u^2}, \quad v' = m\left(u - \frac{uv}{1 + u^2}\right).$$

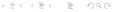
Hopf bifurcation point:  $\alpha_0 = (\sqrt{m^2 + 60} + m)/6$  supercritical if  $0 < m < M_0$ , and subcritical if  $m > M_0$ 

$$M_0 = \frac{\sqrt{19\sqrt{769} - 147}}{2} \approx 9.7453.$$

Example: m = 20, Hopf bifurcation point  $\alpha_0 = 6.908$  (subcritical)

Left:  $\alpha = 6.90$ , Right:  $\alpha = 6.73$ 

(Open Q: how to prove unique or exactly 2 periodic orbits?)



# Stability of $(u_*, v_*)$ w.r.t. R-D system

Linearized operator

$$L(\alpha) := \left( \begin{array}{ccc} \frac{\partial^2}{\partial x^2} + \frac{3\alpha^2 - 5}{1 + \alpha^2} & -\frac{4\alpha}{1 + \alpha^2} \\ \frac{2m\alpha^2}{1 + \alpha^2} & md\frac{\partial^2}{\partial x^2} - \frac{m\alpha}{1 + \alpha^2} \end{array} \right).$$

From Fourier expansion, the eigenvalues of  $L(\alpha)$  are the ones of

$$L_n(\alpha) := \left( egin{array}{ccc} -rac{n^2}{\ell^2} + rac{3lpha^2 - 5}{1+lpha^2} & -rac{4lpha}{1+lpha^2} \ rac{2mlpha^2}{1+lpha^2} & -mdrac{n^2}{\ell^2} -rac{mlpha}{1+lpha^2} \end{array} 
ight), \quad n=0,1,2,\cdots.$$

The characteristic equation of  $L_n(\alpha)$  is

$$\mu^2 - \mu T_n + D_n = 0, \quad n = 0, 1, 2, \cdots,$$

# Stability of $(u_*, v_*)$ w.r.t. R-D system

$$\begin{split} T_n(\alpha) &:= \frac{3\alpha^2 - 5 - m\alpha}{1 + \alpha^2} - \frac{n^2}{\ell^2} (1 + md), \\ D_n(\alpha) &:= m \left[ \frac{5\alpha}{1 + \alpha^2} - \frac{n^2}{\ell^2} \left( \frac{d(3\alpha^2 - 5) - \alpha}{1 + \alpha^2} \right) + \frac{n^4}{\ell^4} d \right], \end{split}$$

Stable: if all  $T_n < 0$  and  $D_n > 0$ , and unstable otherwise

 $T_n = 0$ : possible Hopf bifurcation occurs

 $D_n = 0$ : possible steady state bifurcation (pitchfork) occurs

 $T_0=0$  (3 $\alpha^2-5-m\alpha=0$ ): bifurcation of spatially constant periodic orbit  $D_n=0$  ( $\alpha=0$ ): bifurcation of spatially constant steady state

Other bifurcations: We use  $\alpha > 0$  as bifurcation parameter.

## Spatial Hopf Bifurcation

[Jin-Shi-Wei-Yi, 2013, RMJM]: For any  $n \in \mathbb{N}$ , m > 0, if  $\ell > \sqrt{2/3}n$ , then there exists  $d_* = d_*(m,\ell,n) > 0$  such that when  $0 < d < d_*$ , there exists n+1 points  $\alpha_j^H = \alpha_j^H(d,m,\ell)$ ,  $0 \le j \le n$ , satisfying

$$0 < \alpha_0^H < \alpha_1^H < \alpha_2^H < \dots < \alpha_n^H < \infty;$$

At each  $\alpha=\alpha_j^H$ , the system has a Hopf bifurcation, and the bifurcating periodic solutions near  $(\alpha,u,v)=(\alpha_j^H,\alpha_j^H,1+(\alpha_j^H)^2)$  can be parameterized as  $(\alpha(s),u(s),v(s))$  so that  $\alpha(s)=\alpha_j^H+o(s)$ ,

$$\begin{cases} u(s)(x,t) = \alpha_j^H + s \left( a_n e^{2\pi i t/T(s)} + \overline{a_n} e^{-2\pi i t/T(s)} \right) \cos \frac{n}{\ell} x + o(s), \\ v(s)(x,t) = 1 + (\alpha_j^H)^2 + s \left( b_n e^{2\pi i t/T(s)} + \overline{b_n} e^{-2\pi i t/T(s)} \right) \cos \frac{n}{\ell} x + o(s). \end{cases}$$

[Ni-Tang, 2005]: when d small, there is only the constant steady state.  $\Rightarrow$  when d small and  $\alpha$  large, oscillatory patterns dominate.

# Steady state bifurcation

[Jin-Shi-Wei-Yi]: For any d>0, if  $\widetilde{\ell}_n<\ell<\widetilde{\ell}_{n+1}$  for some  $n\in\mathbb{N}$  and  $\ell$  is not in a countable subset of  $\mathbb{R}^+$ , then there exists n points  $\alpha_j^S=\alpha_j^S(d,\ell),\ 1\leq j\leq n$ , satisfying

$$\alpha_* < \alpha_1^{\mathsf{S}} < \alpha_2^{\mathsf{S}} < \dots < \alpha_n^{\mathsf{S}} < \infty,$$

and  $\alpha=\alpha_n^{\rm S}$  is a bifurcation point for steady state solutions.

- (i) There exists a  $C^{\infty}$  smooth curve  $\Gamma_j$  of steady states bifurcating from  $(\alpha, u, v) = (\alpha_j^S, u_{\alpha_j^S}, v_{\alpha_j^S})$ , with  $\Gamma_j$  contained in a global branch  $\mathcal{C}_j$  of the solution set, and near bifurcation point, the solutions on the curve  $\Gamma_j$  has the form  $u_j(s) = \alpha_j^S + sa_j \cos(k_j x/\ell) + o(s)$ ,  $v_j(s) = 1 + (\alpha_j^S)^2 + sb_j \cos(k_j x/\ell) + o(s)$  for some  $k_j \in \mathbb{N}$ ;
- (ii) Each  $C_j$  is unbounded, that is, the projection of  $C_j$  on the  $\alpha$ -axis contains  $(\alpha_i^S, \infty)$ .

 $\Rightarrow$  when  $\alpha > \alpha_1^S$ , and  $\alpha \neq \alpha_i^S$ , then the system has a non-constant steady state solution.

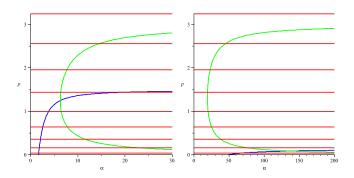
## Global Bifurcation picture

- (i) If  $\alpha < 1.0392$ ,  $(u_*, v_*)$  is globally asymptotically stable;
- (ii) If  $1.0392 < \alpha < 1.2910$ ,  $(u_*, v_*)$  is locally asymptotically stable;
- (iii) If  $1.2910 < \alpha < (\sqrt{m^2 + 60} + m)/6$ , it is Turing instability zone, bifurcation of non-constant steady states, also possible backward Hopf bifurcation;
- (iv) If  $\alpha > (\sqrt{m^2 + 60} + m)/6$ , then many intervening Hopf and steady bifurcations occur as  $\alpha \to \infty$ .

Hopf bifurcation occurs not only when d is small, but also any d>0, but m is small.

Steady state bifurcation also occurs for all d>0 (so not necessarily Turing type).

## Global Bifurcation diagram

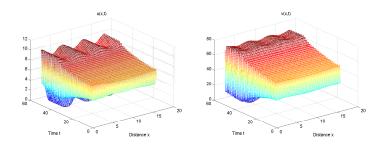


Intersection of green and red curves: Steady state bifurcation points Intersection of blue and red curves: Hopf bifurcation points

Left:Hopf bifurcation first; Right: Steady state bifurcation first



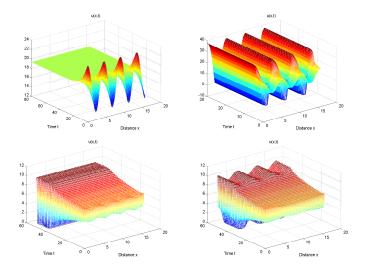
### Spatial non-homogenous periodic solutions



$$u_t = u_{xx} + 5\alpha - u - \frac{4uv}{1 + u^2}, \quad v_t = m\left(dv_{xx} + u - \frac{uv}{1 + u^2}\right),$$

m = 20, primary Hopf bifurcation point  $\alpha = 6.908$  (subcritical)  $\alpha = 6.90$ ,  $u_0(x) = 6 + 0.5\cos(2x/5)$ ,  $v_0(x) = 37 + 0.5\cos(2x/5)$ 

# Bifurcation guided numerics



- (A) to a constant equilibrium; (B) to a non-constant equilibrium
- (C) to a (spatial)-constant periodic solution;



#### Discrete R-D Model

If the spatial domain is "2 points", the model is in a form of 4-D ODE system:

$$\begin{cases} u' = F(u, v) + d_1(w - u), \\ v' = mG(u, v) + d_2m(x - v), \\ w' = F(w, x) - d_1(w - u), \\ x' = mG(w, x) - d_2m(x - v), \end{cases}$$

where

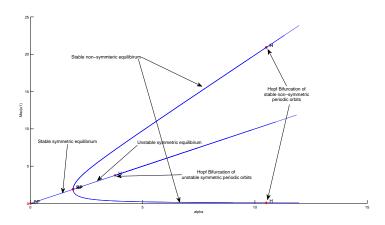
$$F(u, v) = 5\alpha - u - \frac{4uv}{1 + u^2}, \quad G(u, v) = u - \frac{uv}{1 + u^2}.$$

where  $d_1, d_2 > 0$  are the diffusion rates. This is a discrete reaction-diffusion system, or a coupled reaction system.

[Lengyel-Epstein, 1991, Chaos]

Numerical bifurcation software: Auto, MatCont

## Numerical Bifurcation Diagram with MatCont



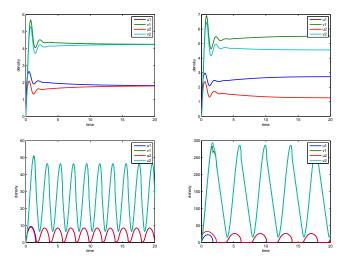
Parameters: m = 10,  $d_1 = 0.1$ ,  $d_2 = 1$ , Turing bifurcation point:  $\alpha_* = 1.904$ 

(primary) Hopf bifurcation point:  $\alpha_0=3.774$ ,

secondary Hopf bifurcation point:  $\alpha_1 = 10.501$ 



#### More numerical simulations



Parameters:  $m=10,\ d_1=0.1,\ d_2=1$  (upper left)  $\alpha=1.8$ ; (upper right)  $\alpha=2$ ; (lower left)  $\alpha=5$ ; (lower right)



#### Remarks

- The result for (semilinear) reaction-diffusion systems can be extended to quasilinear systems with cross-diffusion, self-diffusion, chemotaxis.
  [Liu-Shi-Wang, 2013, DCDSB]
  [Amann, 1991, book chapter] [Da Prado-Lunardi, 1985, AIHP] [Simonett, 1995, DIE]
- The Hopf bifurcation from non-constant equilibria are much difficult to obtain since the linearized operator cannot be decomposed with Fourier series.
- The stability of the bifurcating periodic orbits are difficult to analyze except near the Hopf bifurcation points.
- The Hopf bifurcation theorem is also extended to delay differential equations (see Lecture 6), and delayed reaction-diffusion equations (see Lecture 6).
- **5** The uniqueness of limit cycle is difficult in general.

#### References

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